3.3 Matchings and Factors: Matchings in General Graphs

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Section 3.1 used Hall's Condition to characterize which X,Ybigraphs have an X-saturating matching. We also saw the maximum size matching equals the minimum size vertex cover for bipartite graphs.

Section 3.2 extended this to bipartite matchings and vertex covers for weighted edges, via the Hungarian Algorithm which finds a maximum weight matching with weight equal to a minimum weight cover.

Now in Section 3.3 Tutte's Condition characterizes all graphs having a perfect matching, and more generally the size of a maximum matching in any graph.



<u>3.3.1 Definition</u> A factor of a graph *G* is a spanning subgraph of *G*. A *k*-factor is a spanning *k*-regular subgraph. An **odd component** of a graph is a component of odd order; the number of odd components of *H* is o(H).



Perfect matchings precisely correspond to 1-factors by including the vertices of the graph with the edges of the matching.

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3.3.3 Theorem . (Tutte [1947]) A graph G has a 1-factor if and only if $o(G-S) \le |S|$ for every S⊆V(G).

<u>Proof</u>

(=>) If G has a 1-factor, the odd components of G-S must have at least one vertex each matched to vertices of S.

(<= by contradiction)

Assume Tutte's condition holds and assume to the contrary *G* has no 1-factor. Without loss of generality we may assume:

- 1. G is simple and has no 1-factor.
- 2. G+e has a 1-factor for every $e \notin E(G)$.
- 3. G satisfies Tutte's condition.

Next we justify these 3 assumptions.

Assume Tutte's condition holds and assume to the contrary *G* has no 1-factor. Without loss of generality we may assume:

1. G is simple and has no 1-factor:

Justification

If *G* has no 1-factor, neither does any simple subgraph of *G*. Replace *G* with a simple graph by removing all loops and all but one edge incident to any given pair of vertices.

Note that for every $S \subseteq V(G)$ o(G-S) does not change under this transformation!

Assume Tutte's condition holds and assume to the contrary *G* has no 1-factor. Without loss of generality we may assume:

- 1. G is simple and has no 1-factor.
- 2. G+e has a 1-factor for every $e \notin E(G)$:

Justification

We have a simple graph G with no 1-factor.

- There must exist a supergraph of G on vertices V(G) that is edge-maximal with respect to having no 1-factor.
- For some $e \notin E(G)$, if G+e has no 1-factor, we simply replace G by G+e and repeat.

Now we have a simple G with no 1-factor, but G+e has a 1-factor for every $e \notin E(G)$.

Assume Tutte's condition holds and assume to the contrary *G* has no 1-factor. Without loss of generality we may assume:

- 1. G is simple and has no 1-factor.
- 2. G+e has a 1-factor for every $e \notin E(G)$.
- 3. G satisfies Tutte's condition:

Justification

- We have a simple graph G with no 1-factor but G+e has a 1-factor for every $e \notin E(G)$.
- Now let $S \subseteq V(G)$ be arbitrary. Step 1 did not change o(G-S).

Adding edges to G to get to Step 2 did not increase o(G-S):

G-S contains such an added edge only when both endpoints are within G-S, and its number of odd components can only stay the same or decrease.

(joining components: odd-even -> odd, odd-odd -> even, even-even -> even)

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<u>Proof</u>

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Assume Tutte's condition holds and assume to the contrary *G* has no 1-factor. Without loss of generality we may assume:

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We continue proof of (\leq) with G satisfying Properties 1-3.

<u>Proof of (<=)</u>

Define
$$U = \{v \in V(G) : d(v) = n(G) - 1\}.$$

<u>Case 1</u> The components of G-U are complete graphs.



If n(i) is even, then $K_{n(i)}$ has a perfect matching.

Define $t = |\{i : n(i) \text{ is odd}\}|$. For odd n(i), $K_{n(i)}$ has a matching saturating all but 1 vertex. So far we can match all but *t* vertices in *G*–*U*.

By Tutte's Condition, $t \le |U|$. These *t* vertices are all adjacent to all vertices of *U*, and can be matched to *t* vertices of *U*.

<u>Proof of (<=)</u>

Define $U = \{v \in V(G) : d(v) = n(G) - 1\}.$

<u>Case 1</u> The components of G-U are complete graphs.



The *t* last vertices of the odd complete components of G-U are matched to *t* vertices of *U*.

<u>Claim</u> |U| is even, and so G has a 1-factor after all.

It is easy to see that |U|-t and n(G) have the same parity.

Also, n(G) must be even. Otherwise $|\emptyset| = 0 < 1 \le o(G - \emptyset) = o(G)$.

Complete the 1-factor by pairing the remaining |U|-t vertices of U.

<u>Proof of (<=)</u>

Define $U = \{v \in V(G) : d(v) = n(G) - 1\}$. <u>Case 2</u> Some component of G - U is not complete. Therefore G - U has vertices $x, y, z \in V(G) - U$ with: (1) $d_{G-U}(x,z) = 2$ and $xz \notin E(G)$; $x \quad z$ (2) $xy, yz \in E(G - U)$; and (3) d(y) < n(G) - 1. non-edge

The existence of *y* follows from the distance-2 condition on *x*,*y*. This distance is with respect to G-U, so $y \notin U$.

By definition of *U*, *y* is adjacent to all vertices of *U* but not all vertices of *G*. Therefore G-U has a vertex *w* with:

(4) $yw \notin E(G)$.

<u>Proof of (<=)</u>

Define $U = \{v \in V(G) : d(v) = n(G) - 1\}$. <u>Case 2</u> Some component of G - U is not complete. Therefore G - U has vertices $w, x, y, z \in V(G) - U$ with: (1) $d_{G-U}(x,z) = 2$ and $xz \notin E(G)$; (2) $xy, yz \in E(G-U)$; and (3) d(y) < n(G) - 1; (4) $yw \notin E(G)$.

By assumption that adding any edge to G yields a 1-factor:

(5) G+xz has a 1-factor – call it M_1 ; (6) G+yw has a 1-factor – call it M_2 .

Proof of (<=)

We show it $M_1 \cup M_2 \cup \{xy, yz\}$ contains a 1-factor avoiding $\{xz, yw\}$. Define $F = M_1 \Delta M_2$, which contains both *xz* and *yw*. Fact The components of *F* are even cycles and isolated vertices, because the degree of a vertex in $M_1 \Delta M_2$ is 0 or 2. Define *C* to be the cycle of *F* containing *xz*. Case A *C* does not contain *yw*.

Define a 1-factor on all of G by selecting:

•The edges of M_2 on C

•The edges of M_1 everywhere not on C.



<u>Proof of (<=)</u>

We show it $M_1 \cup M_2 \cup \{xy, yz\}$ contains a 1-factor avoiding $\{xz, yw\}$.

Define $F = M_1 \Delta M_2$, which contains both *xz* and *yw*.

Define C to be the cycle of F containing xz.

Case B C contains yw.

When traveling around C in the direction from v to w,

if z is reached first, define a 1-factor of G by:

Selecting M_1 between v and z on this side;

Selecting the edge yz;

Selecting M_2 on the other side of C; and

Selecting exactly one of M_1 , M_2 off of C.

If *x* is encountered first instead of *z*, replace *yz* with *xz* above.

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