

# Markov Random Field (MRF)

Jacob Goldberger

MRF model:

$$p(x_1, \dots, x_n) = \frac{1}{Z} \prod_i \psi_i(x_i) \prod_{ij \in E} \psi_{ij}(x_i, x_j)$$

Belief Propagation (Sum Product):

$$\begin{aligned} m_{j \rightarrow i}(x_i) &= \sum_{x_j} (\psi_j(x_j) \psi_{ij}(x_i, x_j) \prod_{k \in N(j) \setminus i} m_{k \rightarrow j}(x_j)) \\ b_i(x_i) &= \psi_i(x_i) \prod_{k \in N(i)} m_{k \rightarrow i}(x_i) \end{aligned}$$

Belief Revision (Max Product):

$$\begin{aligned} m_{j \rightarrow i}(x_i) &= \max_{x_j} (\psi_j(x_j) \psi_{ij}(x_i, x_j) \prod_{k \in N(j) \setminus i} m_{k \rightarrow j}(x_j)) \\ \hat{x}_i &= \arg \max_{x_i} (\psi_i(x_i) \prod_{k \in N(i)} m_{k \rightarrow i}(x_i)) \end{aligned}$$

Iterated conditional mode (ICM) algorithm:

$$\hat{x}_i = \arg \max_{x_i} (\psi_i(x_i) \prod_{j \in N(i)} \psi_{ij}(x_i, x_j))$$

Gibbs Sampling:

$$\begin{aligned} p(x_i | x \setminus x_i) &\propto \psi_i(x_i) \prod_{j \in N(i)} \psi_{ij}(x_i, x_j) \\ \hat{p}(x_i = a) &= \frac{1}{n} |\{1 \leq t \leq n | x_i(t) = a\}| \end{aligned}$$

Mean Field Algorithm:

$$q_i(x_i) \propto \exp \left( \log \psi_i(x_i) + \sum_{j \in N(i)} \sum_{x_j} q_j(x_j) \log \psi_{ij}(x_i, x_j) \right)$$